

# CHECKLIST

## BAG GRIPPER

Customer data									
Customer number					Phone number				
Company					E-mail				
Contact									
Project data									
Processed by					Date				
Quantity					Desired date				
Pot. quantity p. a.									
Description of the application									
Attached representation			Drawing			3D model			
Process									
Palletizing			Depalletizing			Bag tearing			
Type of drive									
pneumatic			electric						
Gripping concept									
Undergrip			Needle gripping			Vacuum			
Workpiece information									
Bag material				min. size [mm] (L x W x H)					
Material inside bag				max. size [mm] (L x W x H)					
Abrasive material inside				Weight [kg]					
Packaging		Primary		Secondary		Number of bags		1	2
Picking station									
Picking from			Roller conveyor			Pallet			
Gap between rollers [mm]			Roller pitch [mm]			Roller diameter [mm]			
Environment									
Operating temperature [°C]									
Media exposure		Dust		Coolant		Chemicals		Water spray	
Areas of application		Cleanroom		Food processing area		Potentially explosive atmospheres		Corrosive environment	
Features									
Hold-down device									
Pallet lifter		Pallet type		Size [mm] (L x B x H)		Weight [kg]			
Interlayer lifter		Sheet material		Size [mm] (L x B x H)		Weight [kg]			
Interface									
pneumatic			electric						
Single valve(s)			Valve bank			Valve bank with I/O-block		Valve bank with I/O-module	
Communication									
Profinet			Profibus			Ethernet/IP		EtherCAT	
Robot interface									
Robot/Gantry									