3-JAW INTERNAL GRIPPER

PRODUCT ADVANTAGES



- Dynamic, strong, robust and ready-to-mount gripper on gantry or robot for finish tire handling
- Lightweight, modular industry-standard gripper provides flexibility and ease of use
- A secure and balanced grip reduces the risk of tire deformations
- Sensor mounting to verify the presence of the tire
- Can handle a wide range of tire diameters
- Useful for finished tire handling in the intermediate storage area
- Workpiece contact parts are made of stainless steel

HIGHLIGHTS AND TECHNICAL DATA



Drive AC servo motor



Internal gripping



Gripper jaws are synchronized

CHALLENGE AND SOLUTION

- Interface flange for standard robots and gantries with ready-to-mount solution
- High dynamics and speed with servo operated linear guide mechanism to grip tire
- ▶ Wide range of diameters and weights keeping tire cantered to prevent misalignment
- Suitable for corrosive and humid environments with stainless steel touching components
- Easy maintenance with easy-to-replace parts
- Light and readily available, an economical choice for system integrators
- Low TCO for end users with low cost, high availability and proven design

WORKPIECE PARAMETERS

- Inner diameter [d]: 12-28 inch
- Outer diameter [D]: 450-1250 mm
- Tire height: up to 460 mm
- Single tire weight: up to 100 kg

- Payload: up to 100 kg
- Opening time: 1.5 sec (50 mm radial stroke)
- Closing time: 1 sec (50 mm radial stroke)

BENEFITS IN DETAIL



- 1 Robot mounting plate
- 2 Servo motor with gearbox
- 3 Screw mechanism
- 4 Stainless steel jaws

► VARIANTS

> 3-jaw internal gripper PCR WTR156381



3-jaw internal gripper TBR WTR165197



► TECHNICAL DATA

Order no.	Unit	Workpiece type	Inner workpiece diameter min. [inch]	Inner workpiece diameter max. [inch]	Workpiece weight [kg]
WTR156381	3-jaw internal gripper	Passenger Car Radial (PCR)	12	27	45
WTR165197	3-jaw internal gripper	Truck Bus Radial (TBR)	18	28	100

	► Technical Data		
Order no.	WTR156381	WTR165197	
Workpiece type	PCR	TBR	
Inner workpiece diameter min. [inch]	12	18	
Inner workpiece diameter max. [inch]	27	28	
Opening time (50 mm radial stroke) [sec]	1	1	
Closing time (50 mm radial stroke) [sec]	1.5	1.5	
Gripper weight (without motor) [kg]	65	80	
Gripping concept	Concentric 3-jaw mechanism	Concentric 3-jaw mechanism	
Type of drive*	Servo driven ball screw mechanism suitable for 1FK7043 and equivalent motor	Servo driven ball screw mechanism suitable for 1FK7043 and equivalent motor	

^{*} Please note that the motor, drive and sensors are not included in the scope of supply and can be ordered separately. For different motors, please contact Zimmer Group sales team.