2-JAW RADIAL GRIPPER
SERIES GK

PRODUCT ADVANTAGES

“The compact”

- **Proven technology**
  We have more than 20 years of proven reliability, which ensures uninterrupted production for you

- **Best force/installation space ratio**
  Force transmission using the toggle lever enables high gripping force while optimally utilizing the installation space

- **Smooth stroke configuration**
  You can adjust the 180° opening angle to be unique to your application using an adjusting screw

SERIES CHARACTERISTICS

<table>
<thead>
<tr>
<th>Installation size</th>
<th>Version</th>
</tr>
</thead>
<tbody>
<tr>
<td>GXXX</td>
<td>N</td>
</tr>
<tr>
<td>Spring closing C</td>
<td></td>
</tr>
<tr>
<td>10 million maintenance-free cycles (max.)</td>
<td>●</td>
</tr>
<tr>
<td>Magnetic field sensor</td>
<td>●</td>
</tr>
<tr>
<td>Self locking mechanism</td>
<td>●</td>
</tr>
<tr>
<td>IP20</td>
<td>●</td>
</tr>
</tbody>
</table>

www.zimmer-group.com  ► Data, Drawings, 3-D Models, Operating Instructions


**BENEFITS IN DETAIL**

1. **Buffer stop**  
   - absorption of kinetic energy for heavy and long gripper fingers

2. **Robust, lightweight housing**  
   - Hard-coated aluminum alloy

3. **Stroke adjustment screw**  
   - Infinitely adjustable opening stroke

4. **Guided toggle lever mechanism**  
   - synchronized the movement of the gripper jaws  
   - mechanically self-locking

5. **Mounting block**  
   - mounting for inductive proximity switch

6. **Sensing slot**  
   - mounting and positioning of magnetic field sensors

7. **Integrated gripping force safety device**  
   - spring integrated into cylinder as energy storage

8. **Energy supply**  
   - possible from several sides

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**TECHNICAL DATA**

<table>
<thead>
<tr>
<th>Model</th>
<th>Stroke (mm)</th>
<th>Force (N)</th>
<th>Operating Pressure (bar)</th>
<th>IP Protection</th>
</tr>
</thead>
<tbody>
<tr>
<td>GK15</td>
<td>70-100</td>
<td>0.1-0.12</td>
<td>IP20</td>
<td></td>
</tr>
<tr>
<td>GK20</td>
<td>150-210</td>
<td>0.23-0.3</td>
<td>IP20</td>
<td></td>
</tr>
<tr>
<td>GK25</td>
<td>440-610</td>
<td>0.42-0.58</td>
<td>IP20</td>
<td></td>
</tr>
<tr>
<td>GK35</td>
<td>950-1250</td>
<td>0.9-1.2</td>
<td>IP20</td>
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</tr>
<tr>
<td>GK40</td>
<td>1400-1820</td>
<td>1.7-2.2</td>
<td>IP20</td>
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</tr>
<tr>
<td>GK50</td>
<td>3500-4250</td>
<td>3.5-4.1</td>
<td>IP20</td>
<td></td>
</tr>
</tbody>
</table>

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**FURTHER INFORMATION IS AVAILABLE ONLINE**

All information just a click away at [www.zimmer-group.com](http://www.zimmer-group.com). Find data, illustrations, 3D models and operating instructions for your installation size using the order number for your desired product. Quick, clear and always up-to-date.
2-JAW RADIAL GRIPPER
INSTALLATION SIZE GK20

PRODUCT SPECIFICATIONS

Gripping force diagram
Shows the arithmetic total of the individual forces that occur on the gripper fingers, depending on the gripper finger length.

Forces and moments
Displays static forces and moments that can also have an effect, besides the gripping force.

INCLUDED IN DELIVERY

| 2 [piece] |
| Mounting block KB8K |

RECOMMENDED ACCESSORIES

GRIPPING COMPONENTS

PB20N
Buffer stop

ENERGY SUPPLY

GVM5
Straight Fittings - Quick Connect Style

DRVM5X4
Flow Control Valves - with Swivel joint

SENSORS

NJ8-E2
Inductive proximity switch - Cable 5 m

NJ8-E2S
Inductive proximity switch - Connector M8

MFS01-S-KHC-P1-PNP
Magnetic field sensor angled, cable 0.3 m - M8 connector

MFS02-S-KHC-P1-PNP
Magnetic field sensor straight, cable 0.3 m - M8 connector

CONNECTIONS / OTHER

KAG500
Plug-in connector Straight Cable 5m - Socket M8 (female)

KAW500
Plug-in connector Angled Cable 5m - Socket M8 (female)

ZE20H7X4
Centering Disc

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<table>
<thead>
<tr>
<th>Order no.</th>
<th>GK20N-B</th>
<th>GK20NC-B</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stroke per jaw [°]</td>
<td>90</td>
<td>90</td>
</tr>
<tr>
<td>Gripping moment in closing [Nm]</td>
<td>3</td>
<td>4.2</td>
</tr>
<tr>
<td>Gripping moment secured by spring min. [Nm]</td>
<td></td>
<td>1.2</td>
</tr>
<tr>
<td>Gripping force in closing [N]*</td>
<td>150</td>
<td>210</td>
</tr>
<tr>
<td>Closing time [s]</td>
<td>0.1</td>
<td>0.2</td>
</tr>
<tr>
<td>Opening time [s]</td>
<td>0.1</td>
<td>0.2</td>
</tr>
<tr>
<td>Repetition accuracy +/- [mm]</td>
<td>0.05</td>
<td>0.05</td>
</tr>
<tr>
<td>Operating pressure min. [bar]</td>
<td>3</td>
<td>5</td>
</tr>
<tr>
<td>Operating pressure max. [bar]</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>Nominal operating pressure [bar]</td>
<td>6</td>
<td>6</td>
</tr>
<tr>
<td>Operating temperature min. [°C]</td>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>Operating temperature max. [°C]</td>
<td>&gt;80</td>
<td>+80</td>
</tr>
<tr>
<td>Air volume per cycle [cm³]</td>
<td>9</td>
<td>11</td>
</tr>
<tr>
<td>Weight [kg]</td>
<td>0.23</td>
<td>0.3</td>
</tr>
</tbody>
</table>

*Measured from top edge of housing

**Technical data**

1. Gripper attachment
2. Energy supply
3. Fixing for gripper finger
4. Stroke adjustment screw
5. Integrated slot for magnetic field sensor
6. Fixing for mounting block
7. Buffer stop mounting
A. Air connection (close)
B. Air connection (open)
C. Air connection, alternative (close)
D. Air connection, alternative (open)
GRIPPING COMPONENTS

Buffer stop – PB
Absorption of kinetic energy for heavy and long gripper fingers
The buffer stops are used primarily for fast, unthrottled jaw movements. They are equally suitable for long gripper fingers, high jaw mass and for cycle time optimization. The energy is absorbed by an elastomer damper.

ENERGY SUPPLY

Pneumatic threaded connections
Available in straight and angled design. Can be chosen freely depending on the space conditions or installation situation.
**Inductive sensors – NJ**

The mounting block is aligned to the cam switch, and the sensor is guided into the mounting block until the required switching distance to the cam switch is reached. Fine adjustment can be made by moving the mounting block again. The sensors are available in versions with 5 m cables with exposed leads and 0.3 m cable with connector, as well as with direct plug orientation.
1-point magnetic field sensors – MFS
For non-contact sensing of the piston position
These sensors are installed in the C-groove of the gripper and detect the magnet attached to the piston of the gripper. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFS02, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFS01 is taller, but has a cable outlet that is offset at an angle of 90°. The variants are available in versions with 5 m cables with exposed leads and 0.3 m cable with connector.
2-point magnetic field sensors – MFS
With two freely programmable switching points
Using the programming unit integrated in the cable, two switch points can be freely defined for this sensor. To do so, the sensor is clamped in the C-groove, the gripper approaches position one and the position is taught in using the teach button. Afterwards, the second position is approached with the gripper and programmed. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFS02, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFS01 is taller, but has a cable outlet that is offset at an angle of 90°. The sensors are available in versions with 5 m cables with exposed leads and 0.3 m cable with connector.

Plug-in connectors
For extending and fabricating the connection lines for the sensors
Cables with a length of 5 m with exposed leads are available. Depending on the specific needs, the cables can be shortened or fabricated with connectors in sizes M8 and M12.
Centering disk
Is required in connection with an alignment pin to define the position of the gripper.