# 2-JAW PARALLEL GRIPPERS

# LWR50L-23-00007-A

## **▶ PRODUCT SPECIFICATIONS**

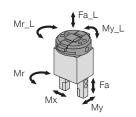


# Gripping force diagram Shows the arithmetic total of the individual forces that occur on the gripper [N] fingers, depending on the gripper finger length 400 250 200 150 100 \_

□= Level 4

#### Forces and moments

Shows static forces and moments



Mr_L [Nm]	20	Mr [Nm]	13
My_L [Nm]	40	Mx [Nm]	13
Fa_L [N]	500	My [Nm]	10
		Fa [N]	325

	► Technical data	
Order no.	LWR50L-23-00007-A	
General data		
Control	I/O	
Operating temperature [°C]	5 +60	
Protection to IEC 60529	IP40	
Weight [kg]	0.97	
Tool changer specific data		
Electrical energy transfer	integrated	
Locking stroke [mm]	1	
Repetition accuracy in X, Y [mm]	0.05	
Repetition accuracy in Z [mm]	0.05	
Tightening force [N]	50	
Release force [N]	0	
Offset at coupling max. in X,Y [mm]	1.0	
Gripper specific data		
Suitable for series	LWR50F-xx-01/02	
Integrated position sensing	Analog 0 to 10 V	
Cable management	external	
Type of drive	electrical	
Stroke per jaw [mm]	13	
Gripping force safety device	mechanical	
Gripping force in closing (adjustable) max. [N]	360	
Gripping force in opening (adjustable) max. [N]	360	
Closing time [s]	0.23	
Opening time [s]	0.23	
Control time [s]	0.055	
Dead weight of mounted gripper finger max. [kg]	0.15	
Length of the gripper fingers max. [mm]	100	
Repetition accuracy +/- [mm]	0.02	
Voltage [V]	24	
Current consumption max. [A]	2	
Minimum positioning path per jaw [mm]	0.5	

## ► RECOMMENDED ACCESSORIES



## **CONNECTIONS / OTHER**



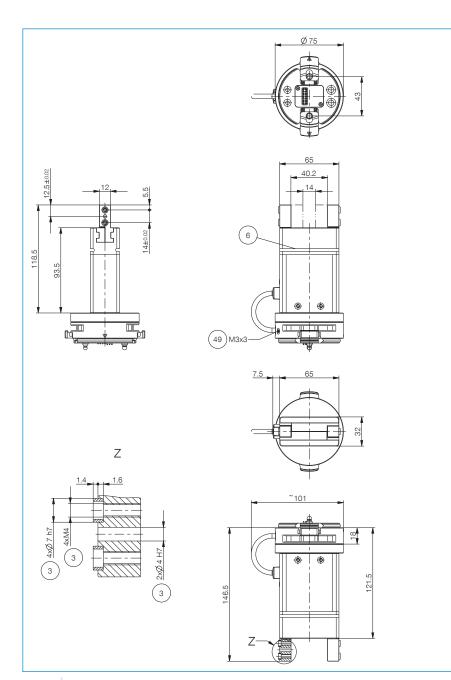
ALWR1-50-A MATCH - Storage station

## ► RECOMMENDED ACCESSORY STORAGE STATION



NJ5-E2SK-01

Inductive Proximity Switch Cable 0,3 m  $\,$  - Connector M8  $\,$ 



- (3) Fixing for gripper finger(6) Integrated slot for magnetic field sensor(49) Ground