## HANDLING SYSTEM FOR BAGS

# Z01SYS137256

#### PRODUCT INFORMATION



The Zimmer Group bag gripper is a one-of-a-kind end-of-arm system for handling bags filled with a wide variety of products. These include flour, fruit, vegetables, grain, fertilizer, chemicals, cement or numerous other products. A variety of bag materials can be used, such as paper, plastic, jute, cloth or fabric. A modular design enables the gripper to be expanded with additional functions such as intermediate layer gripper, pallet handling and much more.

#### **► CHALLENGE**

- Synchronous jaw movement
- Cycle time
- Product variety in shape and size of the content
- Wide variety of bag variants

- ▶ High process flexibility
- Workpiece holding
- Dusty environment

### **SOLUTION**

- Drive synchronized via gear/pinion
- Large drive cylinders for fast cycle times
- Adjustable jaws and strokes for high flexibility
- Variety of jaw geometries and materials

- Function expansion thanks to modular design
- ▶ Temporary force retention via pressure retention mechanism
- Covered mechanical system and dust-protected components

#### **► WORKPIECE**

- ➤ Workpiece weight up to 25kg (up to 100kg by request)
- ▶ Width: 75 to 150mm (filled)

- Length: 600 to 750mm (filled)
- ► Height: 170 to 580mm (filled)

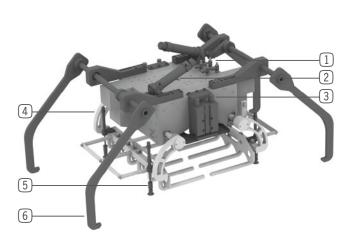


### ► TECHNICAL DATA

Product	Bag
Gripping technology	Form fit
Workpiece weight [kg]	25
System weight [kg]	35
Drive type	Pneumatic



#### **FUNCTIONS IN DETAIL**



- 1 Valve terminal (accessories)
- 2 Robot connecting flange
- 3 Accessories: Pressure unit (height 75 150mm)
- 4 Adjustable jaw width (170 430mm)
- 5 Accessories: Intermediate layer gripper
- 6 Accessories: Pallet gripper

## ► MORE INFORMATION/CROSS REFERENCES

- Pressure unit/hold-down device Z01SYS135374
- Intermediate layer gripper Z01SYS135343
- Pallet gripper Z01SYS135379





