1. Supporting documents



ing documents are available for download on our website. Only the documents currently available on the w

- Drawings, performance data, information about accessory parts, etc.
- Technical data (data sheets)
- · General terms and conditions, including warranty information

Proper use



GW series gripper is only to be used in its original state with its original accessories, with no unauthorized changes at the scope of its defined parameters for use. Zimmer GmbH shall accept no liability for any damage caused by impro

The gripper is designed for operation with compressed air only. It is not suited for operation with other media such as liquids or gases. The gripper is used as defined under "Proper use" in enclosed rooms for time-restricted gripping, handling and holding workpieces. It is not suitable for clamping workpieces during a machining process or for direct contact with perishable goods.

Proper use of the gripper also includes the forces and torques that may be acting in addition to the gripping force. (See product data sheets at www.zimmer-group.com)

Personnel qualifications

Installation, commissioning and maintenance may only be performed by qualified personnel. These persons must have read and understood the installation instructions in full.

Safety notes

- Installation, commissioning, maintenance and repairs may only be performed by qualified experts in accordance with these installation and operating instructions.
- The gripper is state-of-the-art. It is fitted to industrial machines and is used to hold workpieces. The following are examples of situations in which the gripper may cause a hazard the gripper is not properly fitted, used or maintained
 - the gripper is not used for its intended purpose
- failure to observe the local regulations (legislation, guidelines, directives), such as the EC Machinery Directive,
- the Accident Prevention Regulations and the assembly and operating instructions
- The gripper may be used only in accordance with its proper use and technical data ZIMMER GmbH shall accept no liability for any damage caused by improper use.
- Any use other than the proper use requires written approval from Zimmer GmbH
- Do not reach into the operating range of the gripper
- Make sure that the energy supply is disconnected and before you install, retool, maintain or repair the gripper.
- In case of maintenance, renovation or expansion work, remove the gripper from the machine and carry out the work outside the danger zone When commissioning or testing, make sure that the gripper cannot be actuated by mistake.
- Modifications to the gripper, such as adding drill holes or threads, may be made only with prior approval from
- contact our hotline for this purpose.
- Use of the gripper under extreme conditions, such as aggressive liquids and abrasive dust, is subject to prior approval from Zimmer GmbH 10.
- When disassembling grippers with integrated springs, exercise increased caution because spring tension is always present
- 12. When disassembling grippers with integrated springs, exercise increased caution because spring tension is always present

5. Function

The function relies on the action of a pneumatic piston vented on both sides. Alternating ventilation moves the pneumatic piston up and down. The energy generated in this process is transferred to the gripper laws by a kinematic system, producing the gripping force

The MGP series grippers are available in 2 specifications (see technical data):

- Suitable for external and internal gripping
- suitable for external gripping, gripping force safety device in case of pressure failure using integrated Specification NC: The spring integrated into the cylinder chamber is only available for the MGP803 size and higher

1	Robust, lightweight housing Hard-coated aluminum alloy
2	Gripper jaw Individual gripper finger holde
3	Position sensing Permanent magnet for direct sensing of piston movement
4	Integrated gripping force safety device Spring integrated into cylinder chamber as energy storage (for size 803 and higher)
5	Centering sleeve Quick and cost-effective positioning of individual gripper fingers
6	Mounting and positioning Mounting possible from several sides for customized positioning
7	Energy supply Possible from several sides

Mounting and positioning of magnetic field sensors

Fig. 1: MGW gripper



Fig. 2: MGW gripper cross-section



6. Installation

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Integrated slot



Risk of injury in case of unexpected movement of the machine or system into which the gripper—is being installed.

- Switch off the energy supply to the machine before all work
 Secure the machine against being switched on unintentionally
 Check the machine for any residual energy
- **CAUTION:**

- Risk of injury in case of unexpected movement of the gripper when pneumatic energy is connected.
 - ► Switch off the pneumatic energy before all work
 - ➤ Secure the pneumatic circuit against being switched on unintentionally

 Check the pneumatic circuit for any existing residual energy; bleed if ne

6.1 Installing the gripper

The gripper can be fitted on a mounting surface from several sides with the necessary evenness.

Length of the mounting sur- face [mm]	Permitted unevenness [mm]			
<100	<0,02			
>100	<0,05			

two alternative options are available for the installation of the gripper:				
Mounting position	Connection			
Housing floor	00			
Laterally through the housing	1			
Straight pins in the bore holes	13			

Installation and **Operation Instructions**

Im Salmenkopf 5 D-77866 Rheinau **:** +49(0)7844 9138-0

MGW800 DDOC00235

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www.zimmer-group.com

Fax.:+49(0)7844 9138 80

The dimensional drawing for the MGW804 is shown as an example in the adjacent The dimensional drawings can be found on our website.

The dimensions for the design of the mounting pieces can be found on the respective data sheet on our website. You can download the necessary CAD data in all common formats from our web

www.zimmer-group.com

Make the following selections:

Handling technology/grippers/pneumatic/2-jaw parallel grippers/MGW series

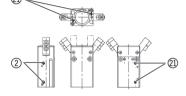
Depending on the size, mounting screws from M3 to M16 and of strength class 8.8

e following tigritering torques must be observed upon installation.										
crew size		МЗ	M4	M5	M6	M8	M10	M12	M14	M16
Permitted tightening torque	[Nm]	1.3	29	6.0	10.2	24.9	49.5	86.3	138.0	214 9

6.2 Accessory installation

Depending on the design size, the pneumatic connections (2) are located on a side surface of the housing or, alternatively, on the bottom surface or rear side of the housing 21).

Connection A ②	Closes the gripper				
Connection B ②	Opens the gripper				
Connection A' (alternative) ②	Closes the gripper				
Connection B' (alternative) ①	Opens the gripper				



0

2

(8)

(15)

0

0

MGW8 \B\



For the available pneumatic connections, refer to the accessories list on the product data sheets on our website. You can also find the necessary ordering information there

6.3 Gripper finger and sensor installation



stalling the gripper fingers, check that they are of a suitable length for the selected gripper variant.

The available accessory is shown on the product data sheets on our website. You can also find the necessary ordering information there

- Insert the centering ring (5) into the provided mating parts on the 2 gripper jaws
- Position the gripper finger on the gripper jaws ② using the centering
- Install the gripper finger with cylinder screws of strength class 8.8 on the gripper jaws

Magnetic field sensors

- Insert the magnetic field sensors bq into the slots 8
- Adjust the magnetic field sensors bg

⇒Refer also to the magnetic field sensor data sheet

7. Technical data

These multi-page data sheets (see example image to the right) contain the following:

- a product description
- the technical data
- a dimensional drawing the available accessories



INFORMATION:

Please gather the technical data from our website www.zimmer-group.com.
This data varies within the series depending on the specific design. If you should have further questions on products or on technical data, please contact ZIMMER GmbH customer service 7.1 Product designation:

Type designation Functional principle N (normally), external and internal gripping Functional principle NC (normally closed), external gripping

8. Maintenance

Maintenance-free operation of the gripper is guaranteed for up to 10 million gripping cycles

The maintenance interval may shorten under the following circumstances

- Operation with compressed air that does not comply with DIN ISO 8573-1 quality class 4 $\,$
- Improper use and use that does not comply with the performance data
- Ambient temperature of more than 60°C: lubricants harden faster! We recommend using the Zimmer GmbH repair service for maintenance and the replacement of seals

Dismantling and re some cases.

9. Declaration of incorporation

In terms of the EU Machinery Directive 2006/42/EC (Annex II 1 B)

Name and address of the manufacturer:

ZIMMER GmbH • Im Salmenkopf 5 • D-77866 Rheinau, Germany • Phone: +49 7844 9138 0 • Fax: +49 7844 9138 80 www.zimmer-group.de

We hereby declare that the incomplete machine described below Product designation: Pneumatic gripper

Type designation: MGW8 \| \bar{\text{N}} \| \bar{\text{N}} \| \bar{\text{N}}

satisfies the following basic requirements of the Machinery Directive 2006/42/EC

No. 1.1.2., No. 1.1.3., No. 1.1.5., No. 1.3.2., No. 1.3.4., No. 1.3.7., No. 1.5.3., No. 1.5.4., No. 1.5.8., No. 1.6.4., No. 1.7.1., No. 1.7.4.

We also declare that the specific technical documents were produced in accordance with Annex VII Part B of this Directive We undertake to provide the market supervisory bodies with electronic versions of special documents for the incomplete machine through our documentation department, should they have reason to request them.

The incomplete machine may only be commissioned if the machine or system in which the incomplete machine is to be installed has been determined to satisfy the conditions of the Machinery Directive 2006/42/EC and the EC Declaration of Conformity has been produced in accordance with Annex II 1 A.

Authorized representative for compiling the relevant technical documents

Kurt Ross siehe Adresse des Herstellers Rheinau, den 04.05.2015 (Place and date of issuance)

Martin Zimmer, Geschäftsführer (Legally binding signature)

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